Op Tracker™

Get smart. Get going.

Get smart and get going with data-driven forest operations that are safer and more efficient. Access the GIS information you need, when and where you need it most.

Op Tracker™ brings powerful GIS technology into the cabs of operations equipment. Operators have a bird's-eye view of the harvest, while forest managers view progress and track analytics in a sophisticated, user-friendly web application from their office.

www.limgeomatics.com

lim GEOMATICS

Turn on Op Tracker™ and crank up productivity with the right data at your fingertips:

- Digital block boundary maps
- Productive machine hours
- Total time of current progress
- Operations timeline

- Block-area completion analysis
- Harvest progress
- Trafficability assessment

Big data, big results

Op Tracker™ is a leap forward for foresters to harness GIS technology. Now you can easily access your GIS information, including advanced forest inventories created from LiDAR data, right on your tablet. Data also syncs to the cloud when Op Tracker™ is within cell service or Wi-Fi range. Plus, when Op Tracker™ is paired with an external Global Navigation Satellite System (GNSS), it provides tracking data that are accurate up to 30 cm, even under forest canopy.

Safe and efficient

Improve safety and efficiency by flagging the perimeter of harvest blocks virtually with the Op Tracker™ built-in alarm system. Proximity warnings for block boundaries, private properties, environmentally sensitive areas and geographic hazards increase the efficiency and safety for each operator and piece of equipment.

Rugged, field-tested technology

Launched in 2014, Op Tracker™ is at work in forests around the world. Lim Geomatics software is built on the ArcGIS platform and is supported by iOS, Android and Windows tablets. We supply custom RAM™ mounts for tablet installation.

Available on the App Store

GET IT ON Google play

Download from Windows Store

ArcGIS Marketplace Provider · esri

For more information, visit: www.limgeomatics.com/optracker